Benefits of reduced levels of energy accommodation for analytic rendezvous trajectories using aerodynamic forces

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Background and research goal

Very Low Earth Orbit (VLEO) offers the unique possibility for propellant less orbit, attitude and formation control via aerodynamic forces (DISCOVERER WP2):

- **Aerodynamic drag:** acts antiparallel to the relative velocity
- **Aerodynamic lift:** acts perpendicular to drag
- \rightarrow Full controllability only with superposition of both forces
- Increased lift forces via reduced levels of energy accommodation (DISCOVERER WP1&3) \rightarrow

Energy accommodation coefficient α :

$$\alpha = \frac{E_I - E_R}{E_I - E_W}$$

Research goal: Quantify influence of energy accommodation on the rendezvous maneuver sequence [6]

Preliminary work [1]

Analysis of the influence of energy accommodation on a robust rendezvous trajectory (circular orbit with 400 km altitude at 10° inclination) using aerodynamic forces using Sentman's GSI model [2] and the **NRLMSISE-00** [3] environment model for moderate solar and geomag. activity. Resulting (average) differential accelerations [10⁻⁵]

m/s²]:	High	Medium	Low
	$\alpha = 1$	$\alpha = 0.91$	$\alpha = 0.7$
a_x = differential lift a_x = differential drag	$a_y = 5.7$	$a_y = 6.6$	$a_y = 7.4$
a_z = differential lift	$a_x = a_z = 0.49$	$a_x = a_z = 1.2$	$a_x = a_z = 2.19$

Rendezvous trajectory algorithm [6,7]

- Analytic rendezvous trajectories using differential aerodynamic forces have a long heritage and are a simple means to gain insights in the methodology [4-6]
- Monte-Carlo based approach (10,000 runs with randomly selected initial conditions) allows for more general statements [7]

Rendezvous is achieved in three successive phases:

- Average in-plane control via differential drag (a_v)
- Out-of-plane control via differential lift (a_z)
- Oscillating motion control via lift (a_x) or drag (a_y)

Example satellite: SOURCE https://www.irs.uni-stuttgart.de/forschung/satellitentechnik-und-instrumente/kleinsatellitenprogramm/page/



Initial condition of third control phase for which the algorithm leads to a successful rendezvous for high (left) medium (central) and low (right) levels of energy accommodation.

Conclusion

By decreasing the energy accommodation coefficient α from 1 to 0.7...

...the average time required to zero out the out-of-plane relative motion can be decreased by around 78%.

...the radius of the feasibility domain of lift can be increased by a factor of 4.3. 2.

Conclusion: Low levels of energy accommodation are beneficial for lift based maneuvers. Still, drag is superior to lift for the in-plane control in any case.

Selected references

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